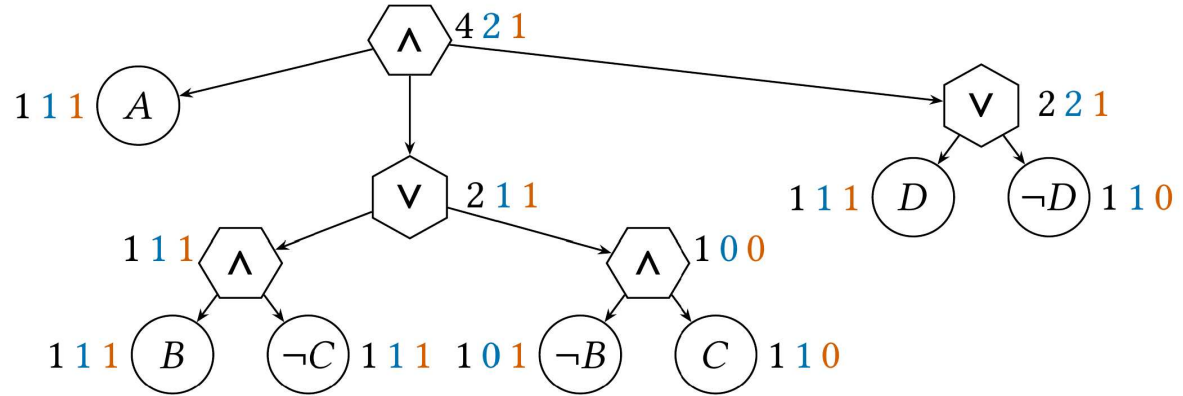




Incorporating Feature-Model Edits with Incremental d-DNNF Compilation

FOSD'25 | Chico Sundermann, Heiko Raab, Thomas Thüm | 28.03.2025

Motivation Product Lines



Your Selection
18-inch 5-spoke alloy wheels
without extra charge



Motivation Product Lines



Your Selection
18-inch 5-spoke alloy wheels
without extra charge



PC BUILDER

GET COMPATIBLE RECOMMENDATIONS
PICK YOUR IDEAL CORSAIR COMPONENTS



Motivation Product Lines

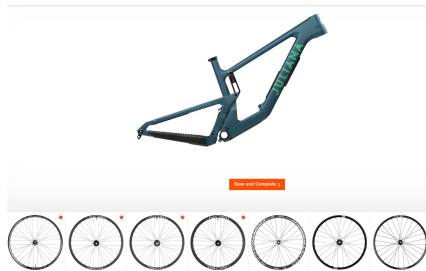


Your Selection
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PC BUILDER

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Motivation Product Lines

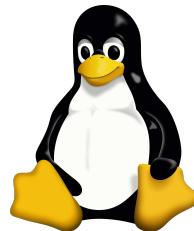
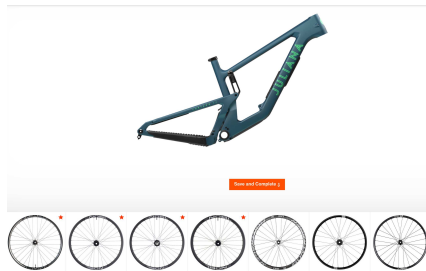


Your Selection
18-inch 5-spoke alloy wheels
without extra charge



PC BUILDER

GET COMPATIBLE RECOMMENDATIONS
PICK YOUR IDEAL CORSAIR COMPONENTS



Motivation Feature Dependencies

 **Compatibility:** Warning! These parts have potential issues or incompatibilities. See [details](#) below.

GROUPSET



Shimano GRX600 2x12sp



Shimano 105 – 2x12



Sram Apex XPLR AXS 1x12



Shimano GRX800 2x12sp



SRAM Rival AXS XPLR – 1x12



Shimano 105 Di2 Disc 2x12



Shimano Ultegra Di2 - 2x12

```
config SECURITY_INFINIBAND
    bool "Infiniband Security Hooks"
    depends on SECURITY && INFINIBAND
```



ASRock B650M Pro RS WiFi Micro ATX AM5

CPU Sockets

CPU_1 (AM5)

Memory Slots

RAM_1 (288-pin DIMM)

RAM_2 (288-pin DIMM)

RAM_3 (288-pin DIMM)

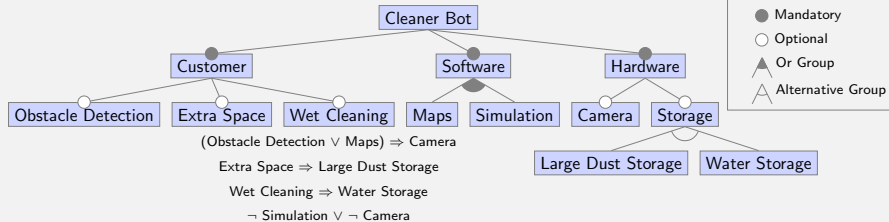
RAM_4 (288-pin DIMM)

Motivation Feature Dependencies

⚠ **Compatibility:** Warning! These parts have potential issues or incompatibilities. See [details](#) below.

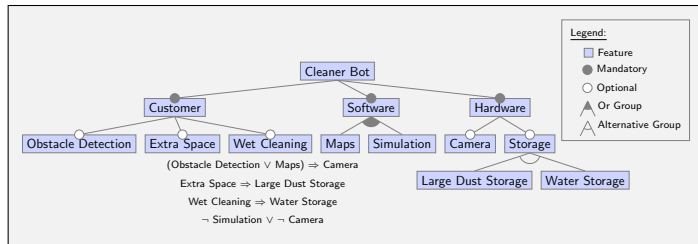
GROUPSET ⓘ

X AM5

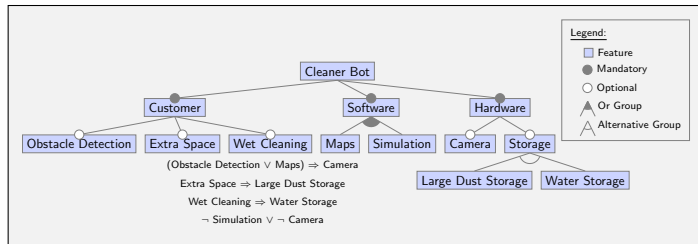


Shimano Ultegra Di2 - 2x12

Motivation Plenty Analyses

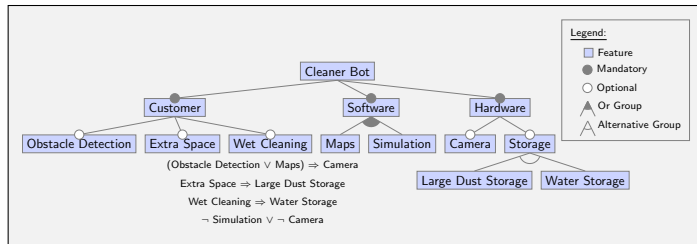


Motivation Plenty Analyses



Can we configure a robot?

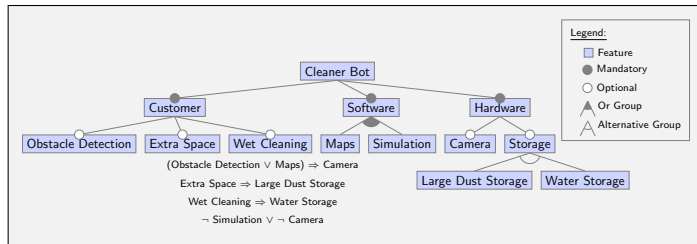
Motivation Plenty Analyses



Can we configure a robot?

Is there a robot with camera?

Motivation Plenty Analyses

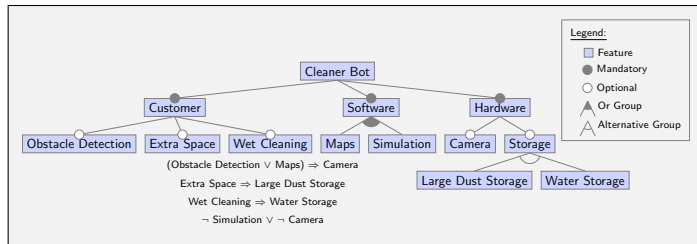


Can we configure a robot?

Is there a robot with camera?

How many robots?

Motivation Plenty Analyses



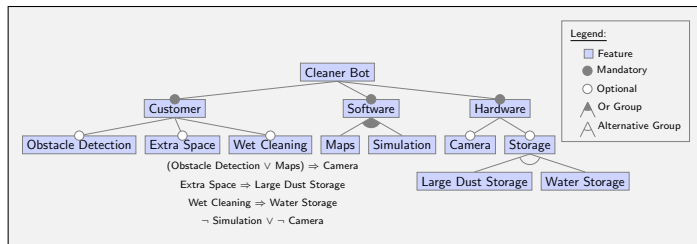
Can we configure a robot?

Is there a robot with camera?

How many robots?

Which robots to test?

Motivation Plenty Analyses



Can we configure a robot?

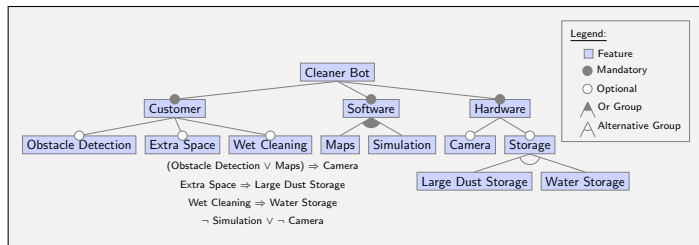
Is there a robot with camera?

How many robots?

Which robots to test?

$\text{Customer} \wedge \text{Software} \wedge (\text{Maps} \vee \text{Simulation}) \wedge \dots$

Motivation Plenty Analyses



Can we configure a robot?

Is there a robot with camera?

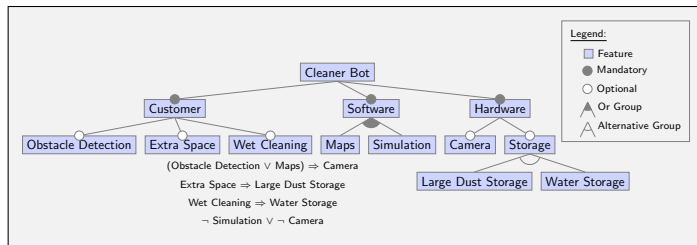
How many robots?

Which robots to test?

$\text{Customer} \wedge \text{Software} \wedge (\text{Maps} \vee \text{Simulation}) \wedge \dots$



Motivation Plenty Analyses



Can we configure a robot?

Is there a robot with camera?

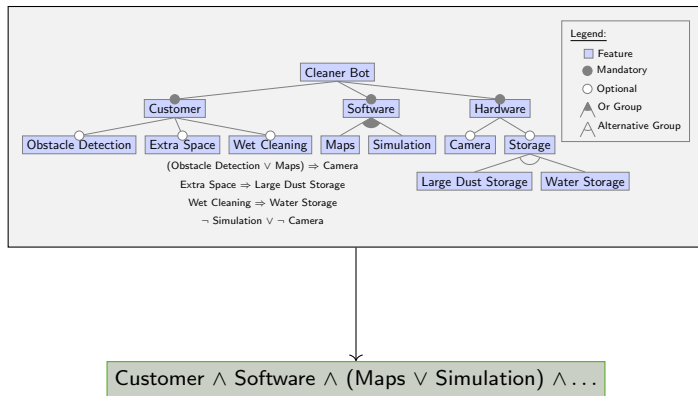
How many robots?

Which robots to test?

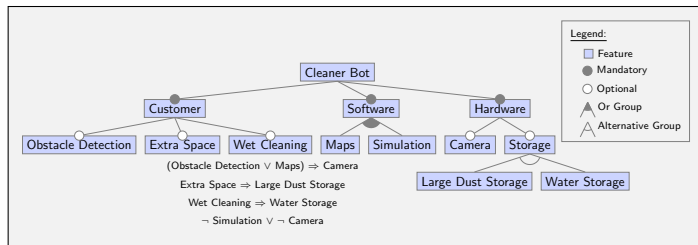
Customer $\wedge$ Software $\wedge$ (Maps $\vee$ Simulation) $\wedge$...



Motivation Knowledge Compilation

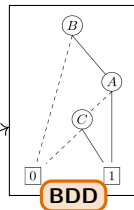


Motivation Knowledge Compilation

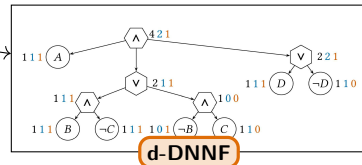


$\text{Customer} \wedge \text{Software} \wedge (\text{Maps} \vee \text{Simulation}) \wedge \dots$

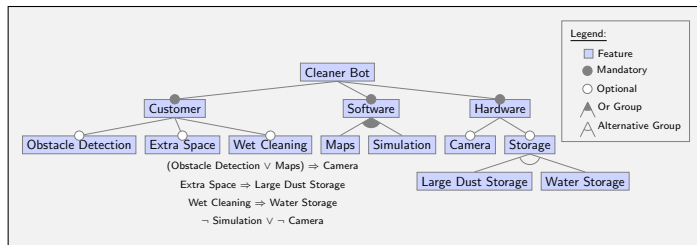
Compile



Compile



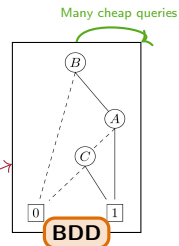
Motivation Knowledge Compilation



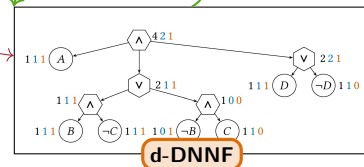
$\text{Customer} \wedge \text{Software} \wedge (\text{Maps} \vee \text{Simulation}) \wedge \dots$

One-time expensive

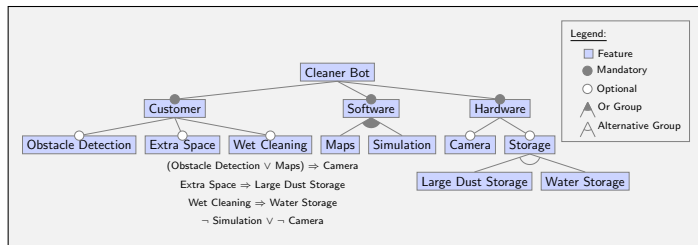
Many cheap queries



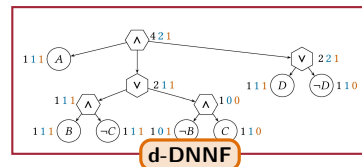
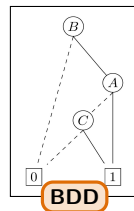
One-time expensive



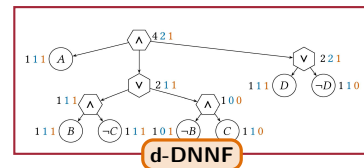
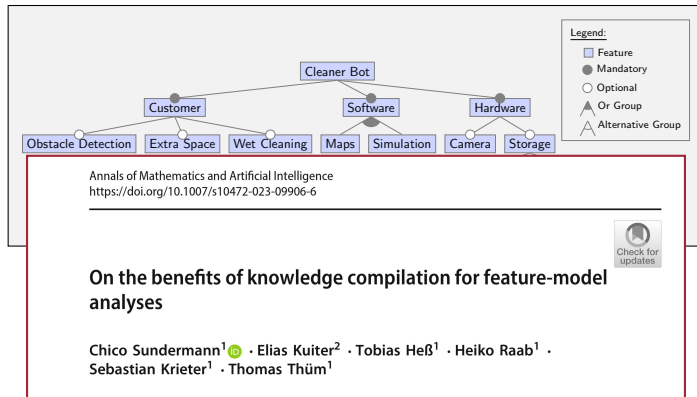
Motivation Knowledge Compilation



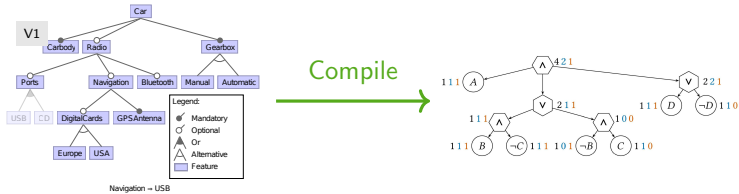
$\text{Customer} \wedge \text{Software} \wedge (\text{Maps} \vee \text{Simulation}) \wedge \dots$



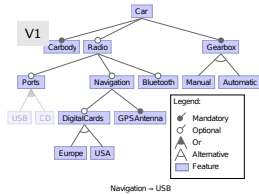
Motivation Knowledge Compilation



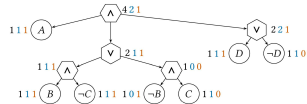
Incremental d-DNNF Compilation



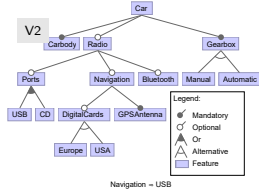
Incremental d-DNNF Compilation



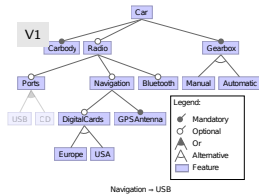
Compile



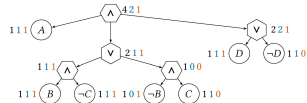
Evolve



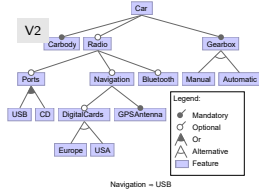
Incremental d-DNNF Compilation



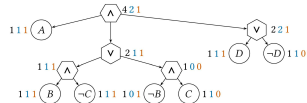
Compile



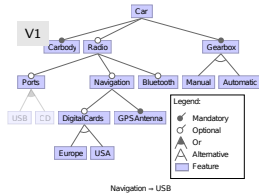
↓ Evolve



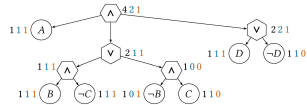
Compile



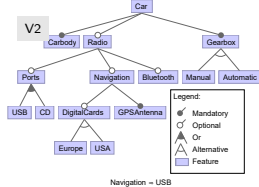
Incremental d-DNNF Compilation



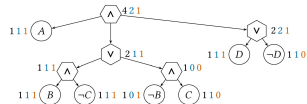
Compile



Evolve



Compile

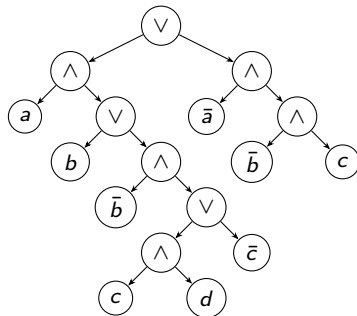


Adapt

Approach Identify Part Requiring Update

- Recurse d-DNNF to find parts sharing variables with clause
- Apply assumptions while recursing to skip parts unchanged by clause

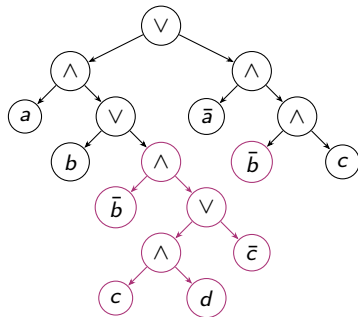
Change: $b \vee d$



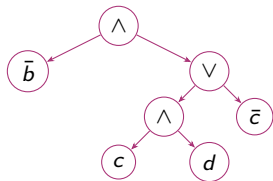
Approach Identify Part Requiring Update

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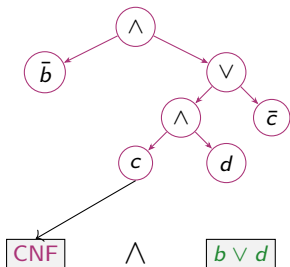
Change: $b \vee d$



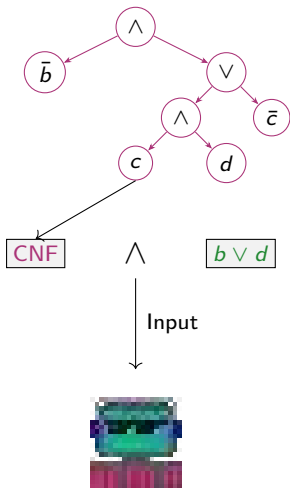
Approach Partially Recompile & Reattach



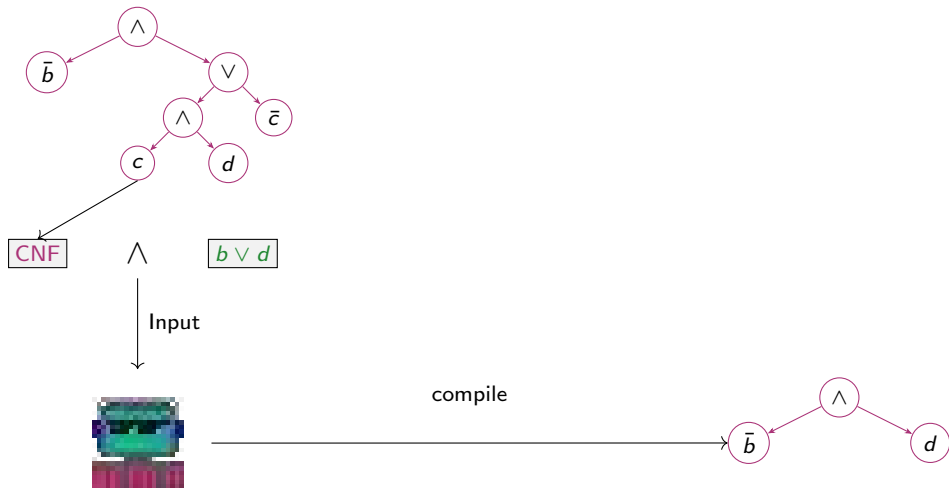
Approach Partially Recompile & Reattach



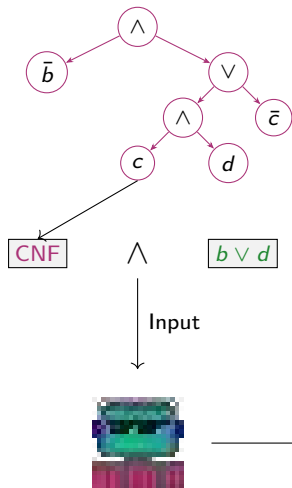
Approach Partially Recompile & Reattach



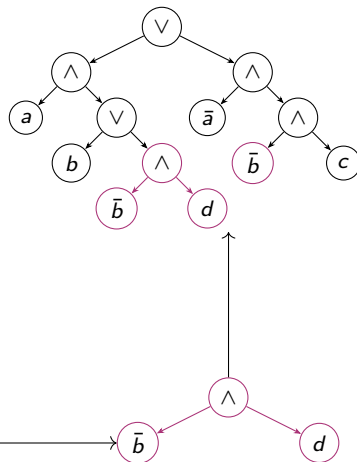
Approach Partially Recompile & Reattach



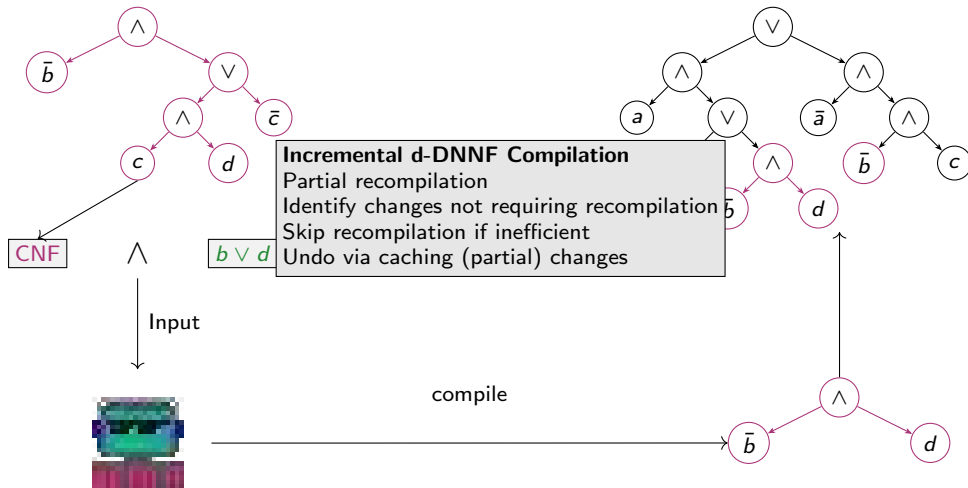
Approach Partially Recompile & Reattach



compile



Approach Partially Recompile & Reattach



Evaluation Experiment Design

- Goal: Examine performance benefits

Domain	Models	Features	Clauses	Cardinality
automotive	2	2,513 – 18,616	10,311 – 350,149	$5.3^{210} - 1.7^{1534}$
business	1	1,920	61,362	2.0^{397}
cloud	1	106	156	5.4^{20}
database	1	117	417	3.2^1
deep-learning	2	3,296 – 6,867	8,004 – 17,431	$1.3^{185} - 2.8^{630}$
e-commerce	2	287 – 2,238	421 – 2,615	$2.3^{49} - 8.0^{558}$
finance	3	176 – 771	280 – 7,238	$9.7^{13} - 5.3^{31}$
games	1	144	769	4.2^{18}
hardware	2	172 – 377	309 – 1,356	$3.3^{21} - 2.3^{27}$
navigation	2	103 – 145	185 – 378	$3.2^{10} - 1.8^{12}$
security	1	158	457	1.2^{14}
systems software	14	96 – 1,580	183 – 15,692	$8.3^{11} - 4.1^{409}$
text	1	137	179	1.3^{23}

Evaluation Experiment Design

- Goal: Examine performance benefits
- Subject systems
 - Industrial feature Models
 - Various domains, sizes

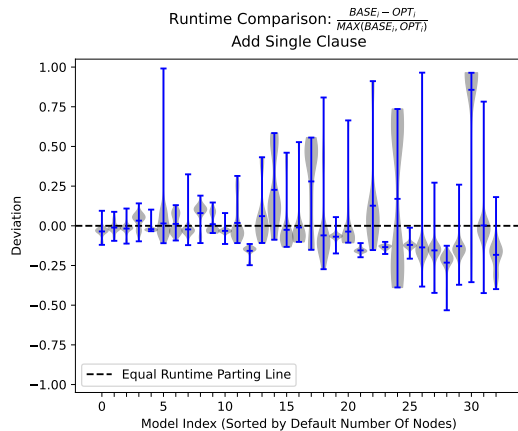
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Evaluation Experiment Design

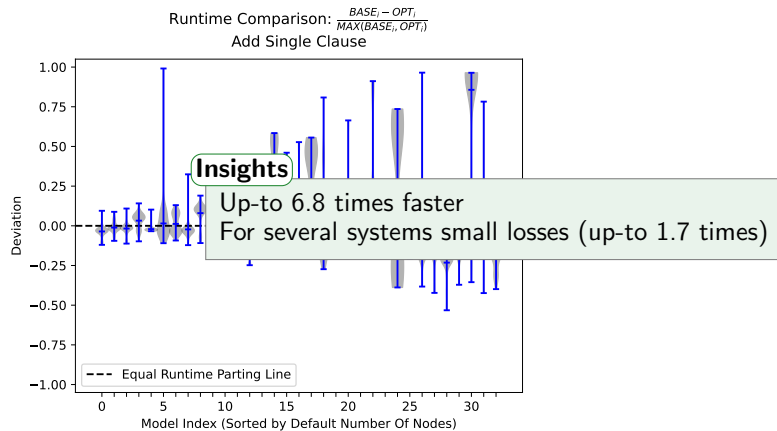
- Goal: Examine performance benefits
- Subject systems
 - Industrial feature Models
 - Various domains, sizes
- Emulate realistic changes
 - Remove one constraint → Compile without
→ Incrementally add removed
 - Apply typical edit patterns e.g.:
 - Add/remove feature
 - Change feature group
 - Move feature

Domain	Models	Features	Clauses	Cardinality
automotive	2	2,513 – 18,616	10,311 – 350,149	$5.3^{210} - 1.7^{1534}$
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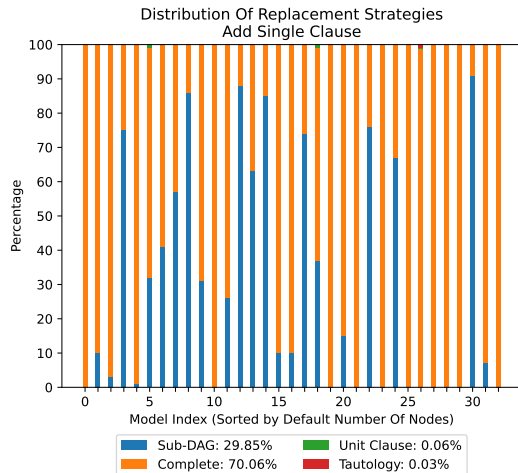
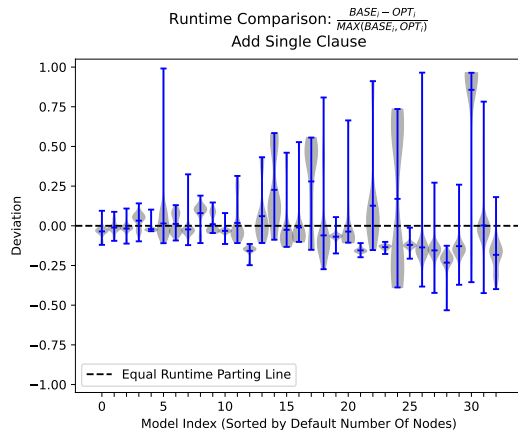
Evaluation Single Clause



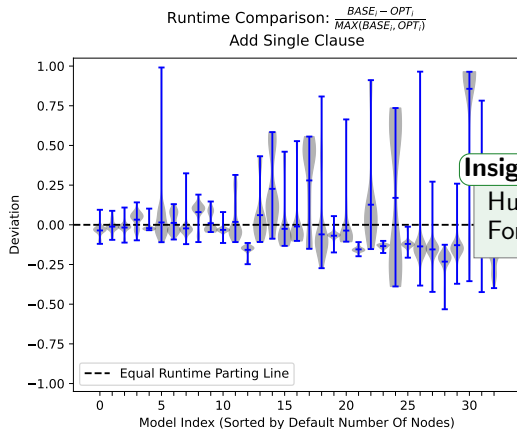
Evaluation Single Clause



Evaluation Single Clause

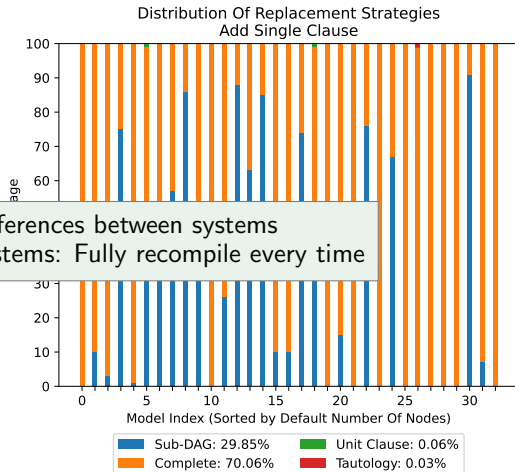


Evaluation Single Clause

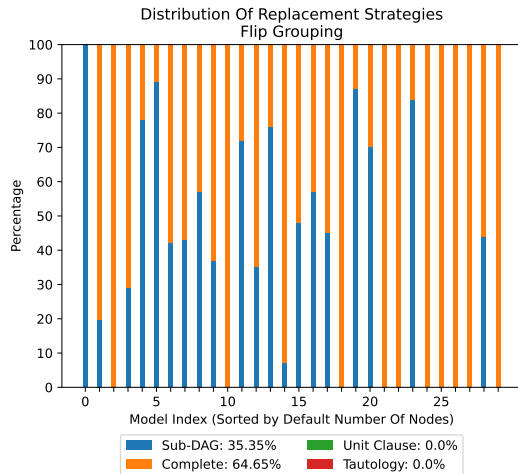
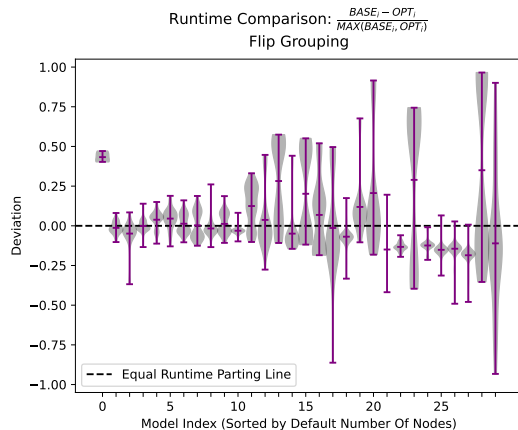


Insights

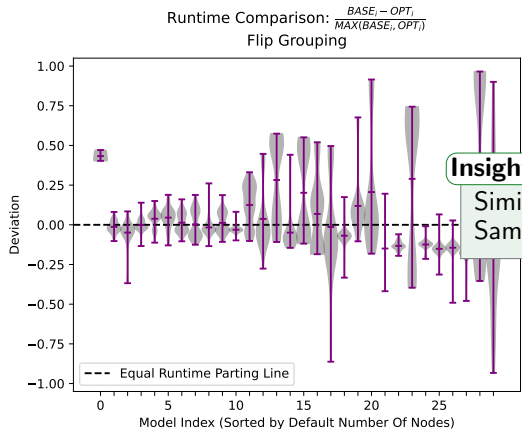
Huge differences between systems
For 6 systems: Fully recompile every time



Evaluation Flip Group

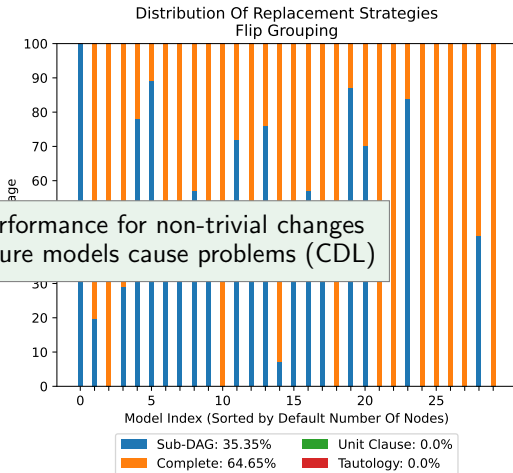


Evaluation Flip Group

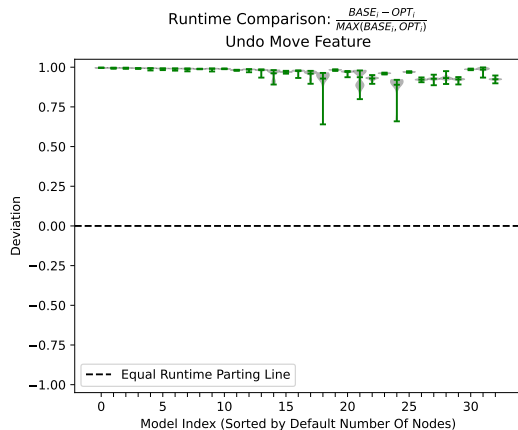
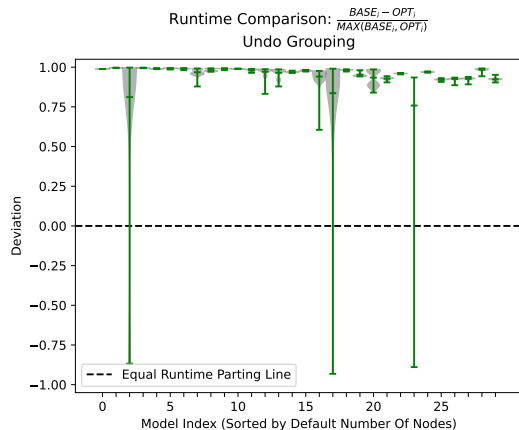


Insights

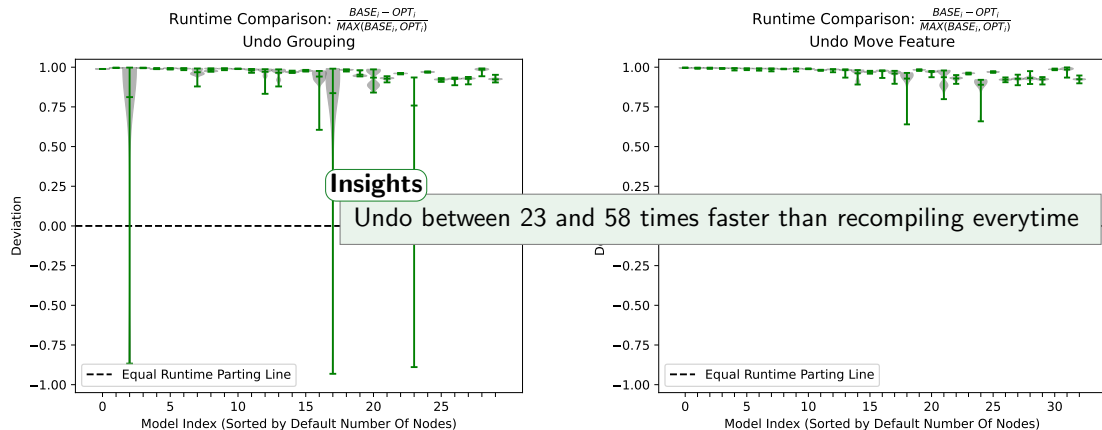
Similar performance for non-trivial changes
Same feature models cause problems (CDL)



Evaluation Undo



Evaluation Undo



Conclusion & Outlook

Insights

Substantial runtime improvements for some feature models
Undo by caching performs very well

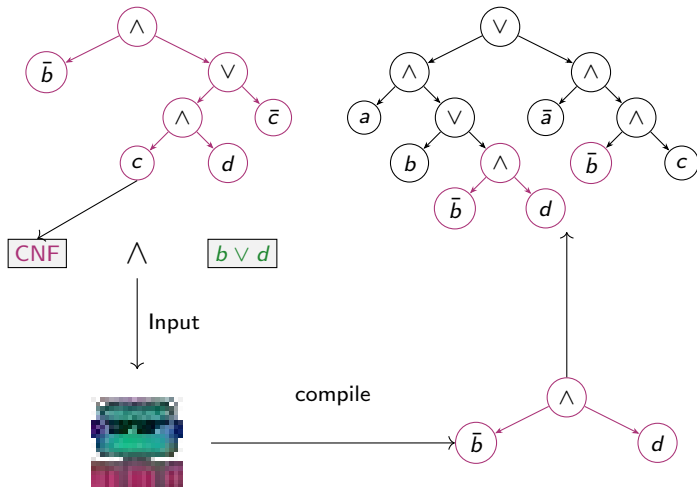
Limitations

Performance highly depends on input model
Some models always need full recompilation

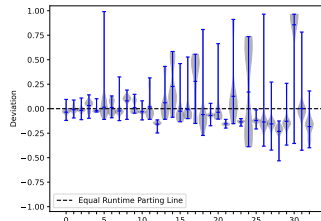
Future Work

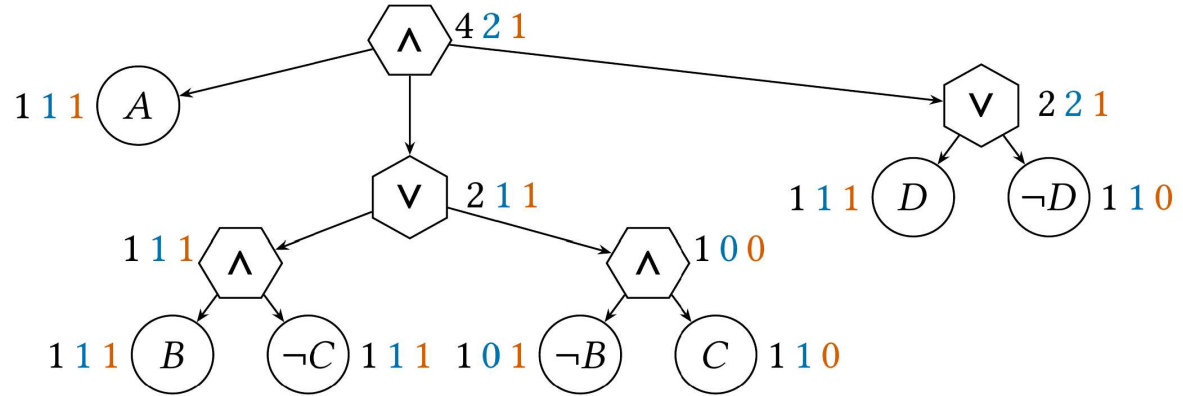
How to improve for unfavourable d-DNNFs?
How to prepare the initial d-DNNF to be more favourable?
How to recognize hopeless d-DNNFs?

Incorporating Feature-Model Edits with Incremental d-DNNF Compilation



Runtime Comparison: $\frac{BASE - OPT}{MAX(BASE, OPT)}$
Add Single Clause





Incorporating Feature-Model Edits with Incremental d-DNNF Compilation

FOSD'25 | Chico Sundermann, Heiko Raab, Thomas Thüm | 28.03.2025

Incorporating Feature-Model Edits with Incremental d-DNNF Compilation

1. Motivation

Product Lines
Feature Dependencies
Plenty Analyses

Knowledge
Compilation

2. Approach

3. Evaluation

Experiment Design

Single Clause

Flip Group

Undo

4. Conclusion & Outlook

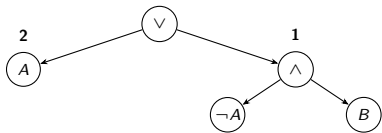
5. Future Work

What's left to do?
Content Overview

How does this even work? d-DNNFs (Darwiche 2000)

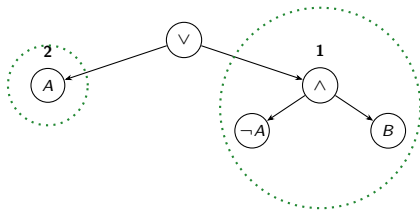
deterministic
decomposable
negation
normal
form

How does this even work? d-DNNFs (Darwiche 2000)



deterministic
decomposable
negation
normal
form

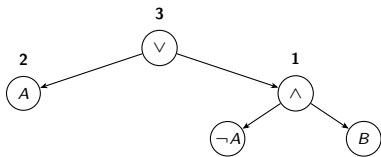
How does this even work? d-DNNFs (Darwiche 2000)



No shared solutions

deterministic
decomposable
negation
normal
form

How does this even work? d-DNNFs (Darwiche 2000)



deterministic (Sum for $\vee$)

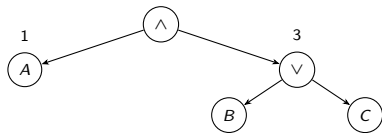
decomposable

negation

normal

form

How does this even work? d-DNNFs (Darwiche 2000)



deterministic (Sum for $\vee$)

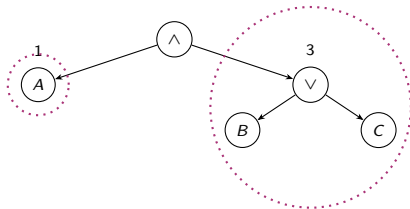
decomposable

negation

normal

form

How does this even work? d-DNNFs (Darwiche 2000)



Independent
⇒ All pairs valid

deterministic (Sum for $\vee$)

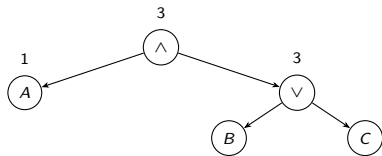
decomposable

negation

normal

form

How does this even work? d-DNNFs (Darwiche 2000)



deterministic (Sum for $\vee$)
decomposable (Product for $\wedge$)
negation
normal
form