



Tailoring Hypergraph Partitioning for Efficient d-DNNF Compilation

Jan Baudisch | 25.03.2025

Knowledge Compilation

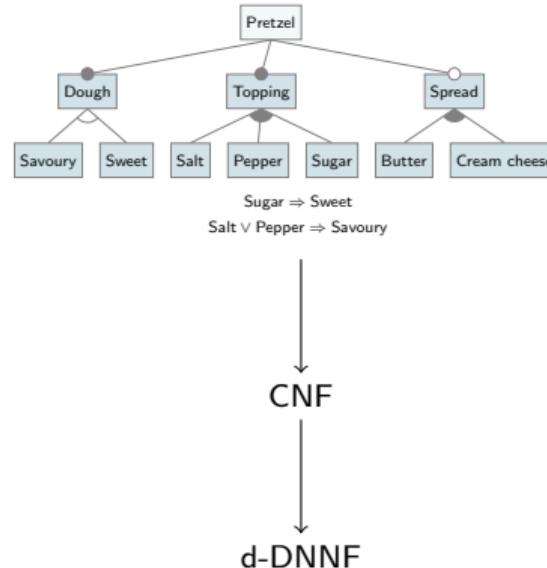
Feature Model Analysis

Expensive queries:

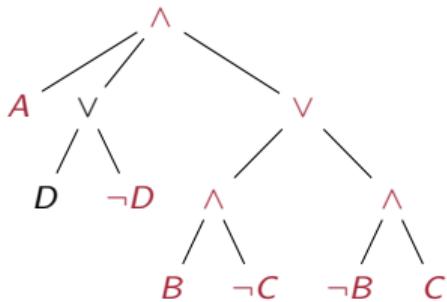
- Counting
- SAT
- Sampling
- Queries with assumptions
- ...

Knowledge Compilation

Transforming feature models into a format suitable for multiple (faster) analyses.



d-DNNF



d-DNNF

- Negation normal form: Negation only in literals
- Decomposable \wedge : Subtrees do not share variables
- Deterministic \vee : Subtrees are logically contradictory

Benefit

Analyses like SAT and counting in linear time.

d-DNNF Compilation

d4 d-DNNF Compiler

CNF → d-DNNF by using exhaustive DPLL

Variable Decision

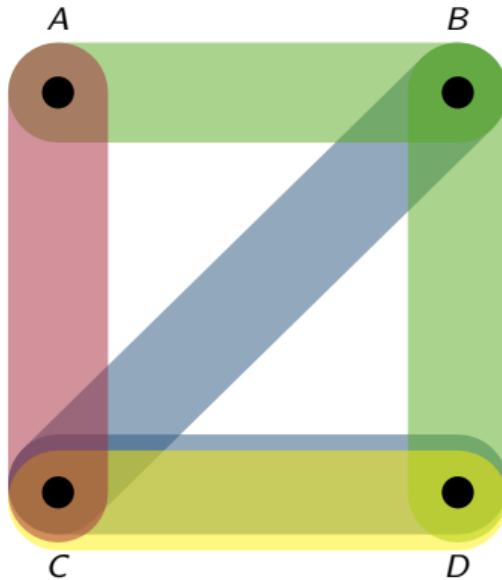
The branching variable has an impact on the overall runtime.

```
input : CNF formula  $F$ 
output: d-DNNF of  $F$ 

1  $S \leftarrow solve(F);$ 
2 if  $S = \emptyset$  then return  $\perp$ ;
3 if  $F = \emptyset$  then return  $andNode(S, \top)$ ;
4 components  $\leftarrow split(F);$ 
5 sub  $\leftarrow \{\};$ 
6 for  $C \in components$  do
7    $V \leftarrow choose(C);$ 
8   node  $\leftarrow orNode(V, d4(C|V), d4(C|\neg V));$ 
9   add(sub, node);
10 end
11 return  $andNode(S, sub);$ 
```

Hypergraphs

$$(B \vee C \vee D) \wedge (A \vee B \vee D) \wedge (A \vee C) \wedge (C \vee D)$$



Hypergraph

Generalization of graphs: nets (edges) contain many vertices.

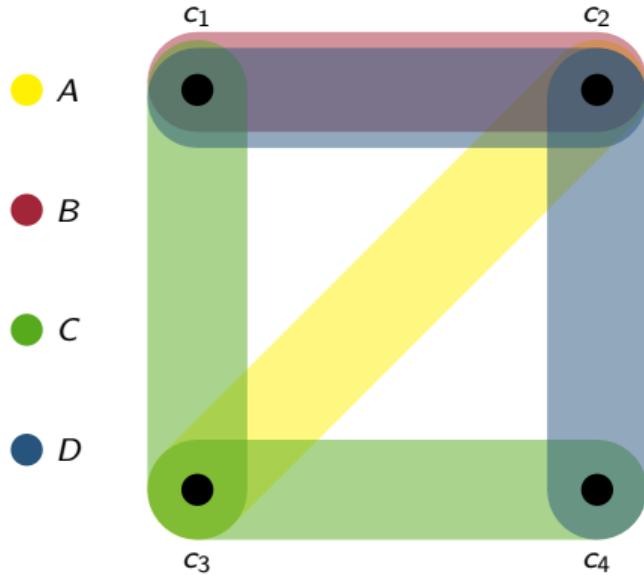
$$H = (V, N)$$

CNF Representation

Variables \rightarrow Vertices
Clauses \rightarrow Nets

Dual Hypergraphs

$$(B \vee C \vee D) \wedge (A \vee B \vee D) \wedge (A \vee C) \wedge (C \vee D)$$



Dual Hypergraph

Vertices and nets switch roles.

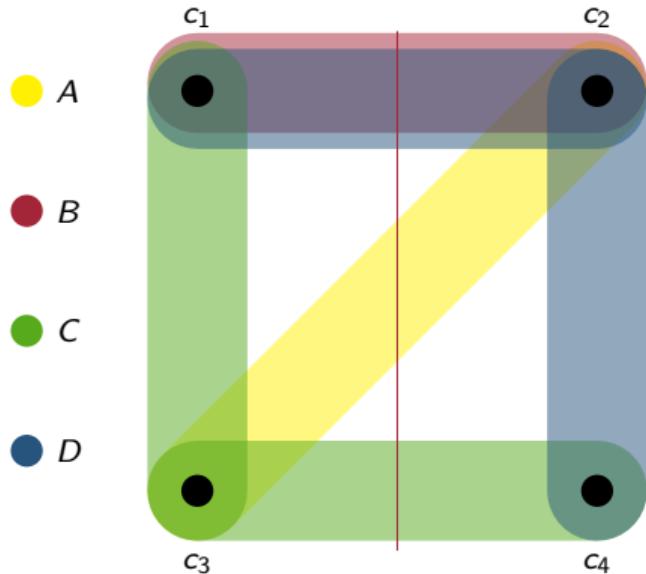
$$H = (V, N)$$
$$H^* = (N, V)$$

CNF Representation

Variables \rightarrow Nets
Clauses \rightarrow Vertices

Hypergraph Partitioning

$$(B \vee C \vee D) \wedge (A \vee B \vee D) \wedge (A \vee C) \wedge (C \vee D)$$



Partitioning

Division of the hypergraph into k blocks while optimizing a given metric.

Cutset

Nets containing vertices in multiple blocks.

Result

Cutset \rightarrow Variables (to be decided)
Blocks \rightarrow Clauses (components)

d-DNNF Compilation

Variable decision

Cutset assignment → disconnected components

```
input : CNF formula  $F$ 
output: d-DNNF of  $F$ 

1  $S \leftarrow solve(F);$ 
2 if  $S = \emptyset$  then return  $\perp$ ;
3 if  $F = \emptyset$  then return  $andNode(S, \top)$ ;
4 components  $\leftarrow split(F);$ 
5  $sub \leftarrow \{\};$ 
6 for  $C \in components$  do
7    $V \leftarrow choose(C);$ 
8    $node \leftarrow orNode(V, d4(C|V), d4(C|\neg V));$ 
9    $add(sub, node);$ 
10 end
11 return  $andNode(S, sub);$ 
```

Research Questions

Existing partitioners

Performance for d-DNNF compilation?

CNF and hypergraph metrics

Correlation CNF/hypergraph metrics → difficulty of resulting formulas?

New partitioner

Specifically for DPLL style algorithms

Dataset

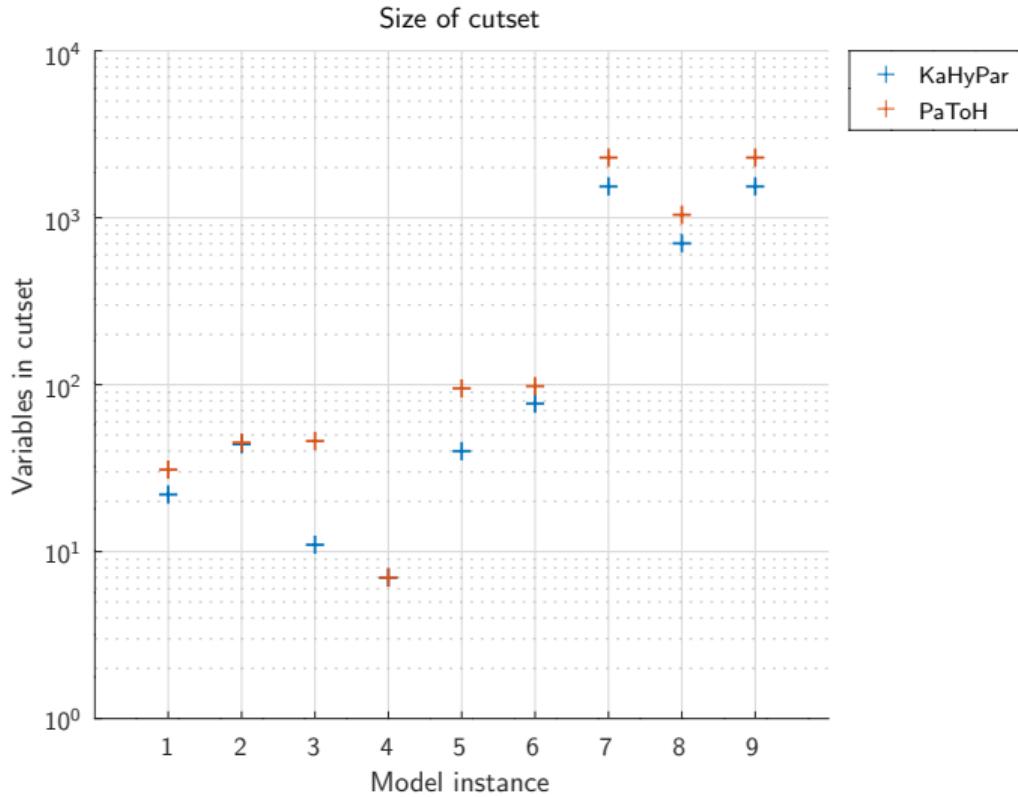
Source

- Feature Model Benchmark
- Industry models

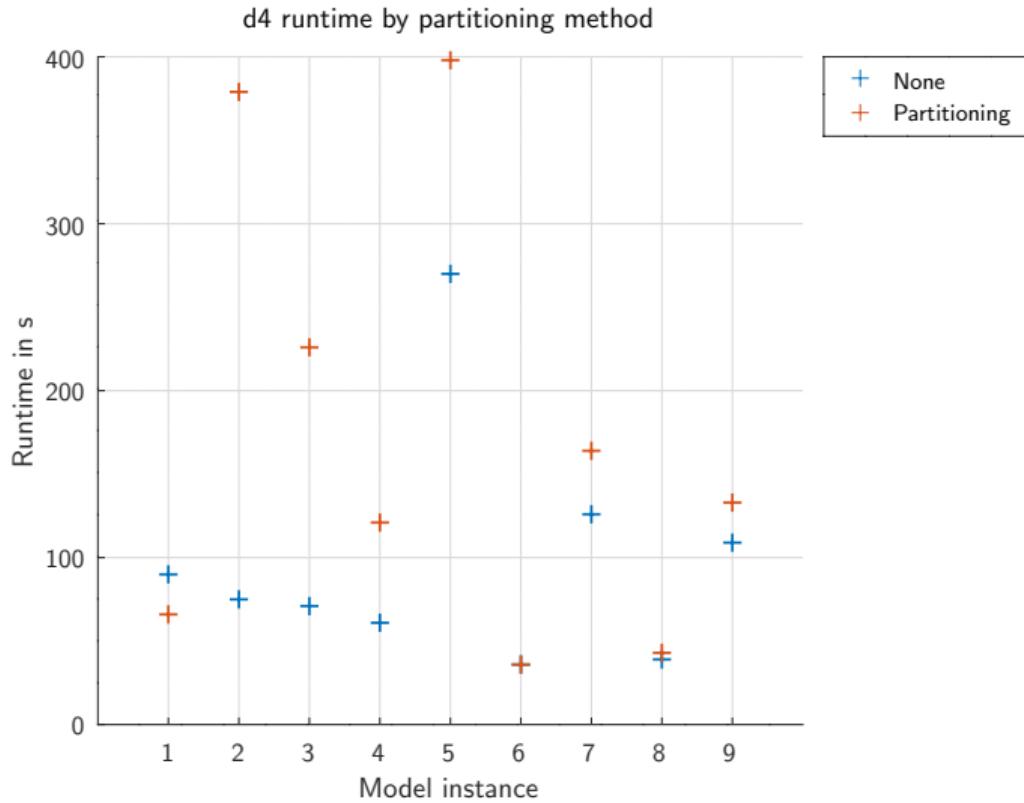
Filter

Solvable by d4 in 10s...2h

Cut Size



Performance



Improvements

Current state

Unweighted partitioning

CNF → unweighted hypergraph → partition

Fixed block size

Input CNF → 2 blocks

Possible improvements

Weighted partitioning

Net weights based on heuristics, e.g. $DLCS(v)$ = occurrences of variable v in CNF

Community detection

Community detection algorithm → dynamic block size

Improvements

Current state

Static partitioning

Decomposition tree precalculated before DPLL

Cut based partitioning

Partitioners optimize cut size/weight

Possible improvements

Dynamic partitioning

New hypergraph for each sub-problem

Feature model based partitioning

Feature model subtrees → blocks based on cross-tree constraints

Weighted Partitioning

MAXO (DLCS)

$MAXO(V) = \text{occurrences of } V$

MOMS

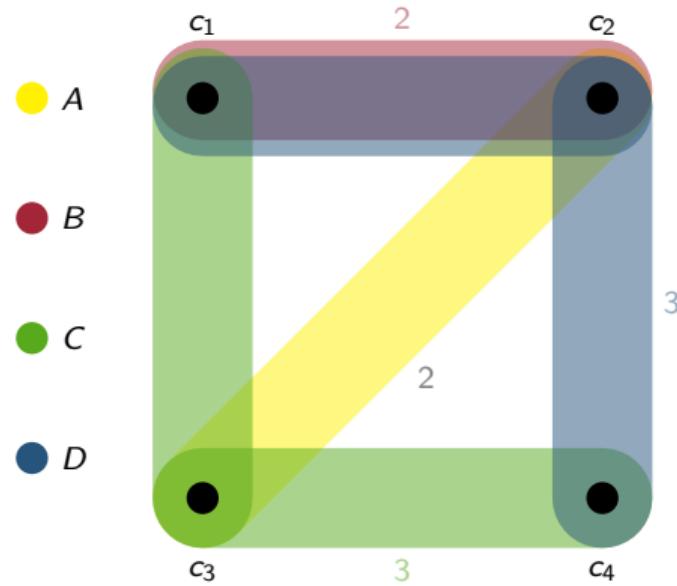
$MOMS(V) = \text{occurrences of } V \text{ in minimal clauses}$

MAMS

$MAMS(V) = MAXO(V) + MOMS(V)$

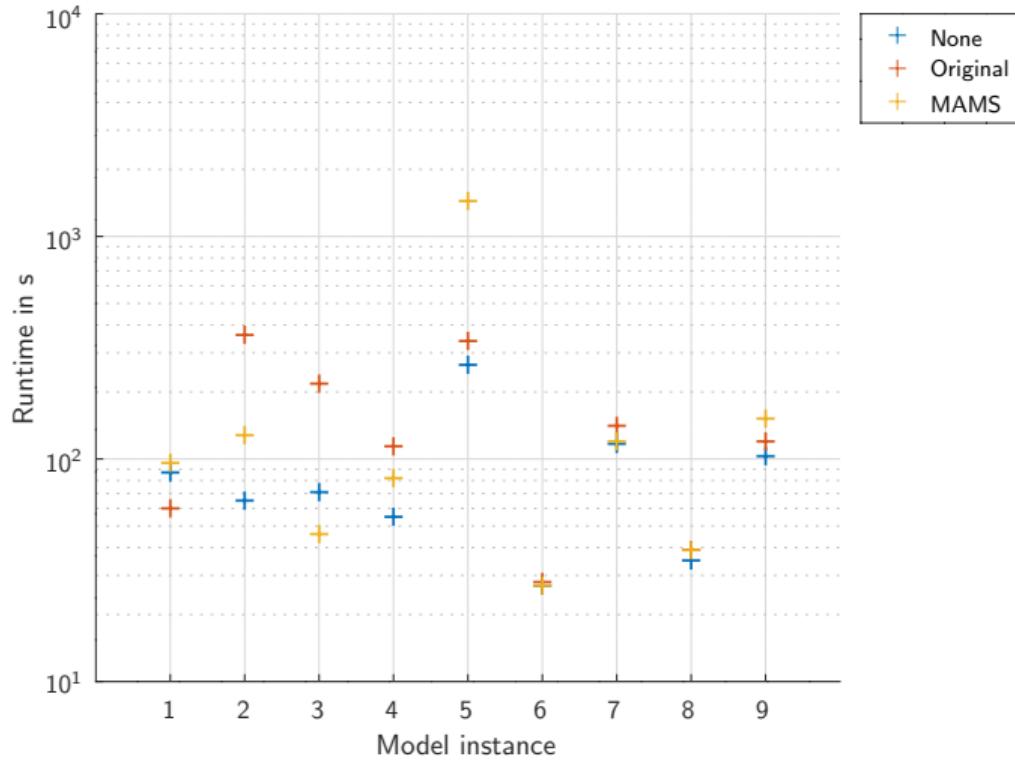
MAXO

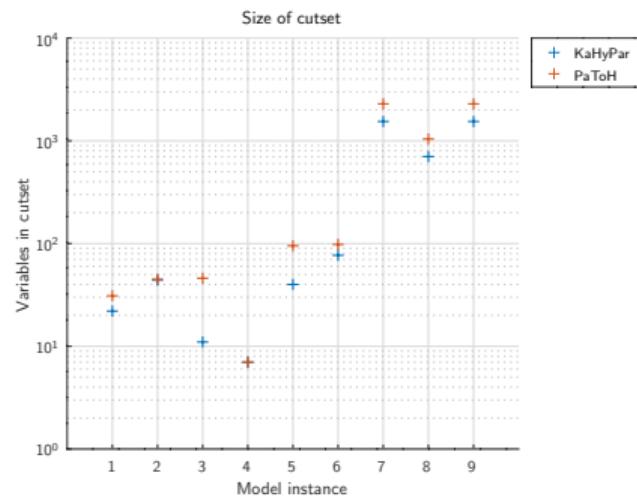
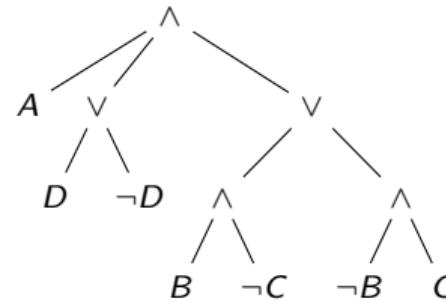
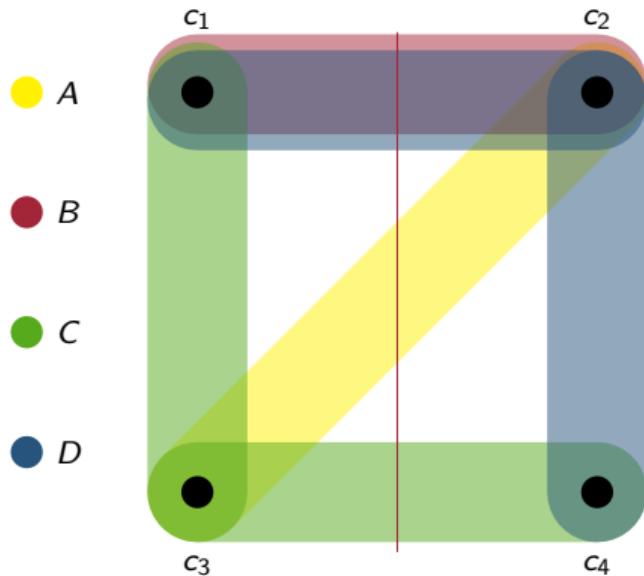
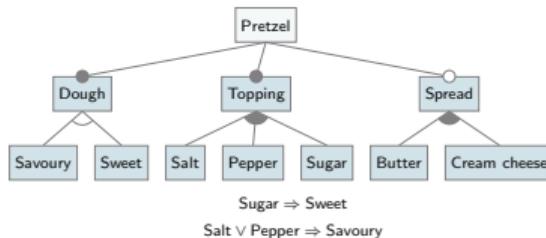
$$(B \vee C \vee D) \wedge (A \vee B \vee D) \wedge (A \vee C) \wedge (C \vee D)$$



Weighted Partitioning

d4 runtime by partitioning method





Tools

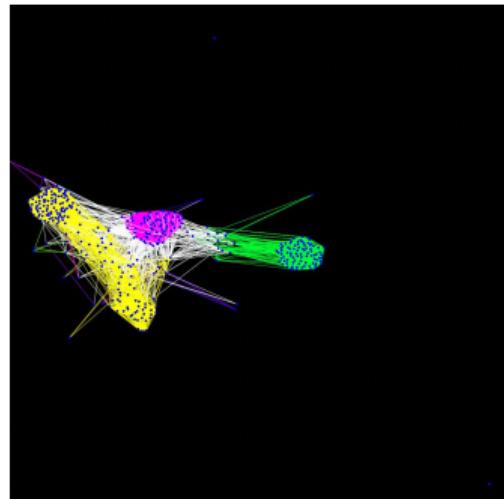
ddnnife d-DNNF reasoner

github.com/SoftVarE-Group/d-dnnf-reasoner

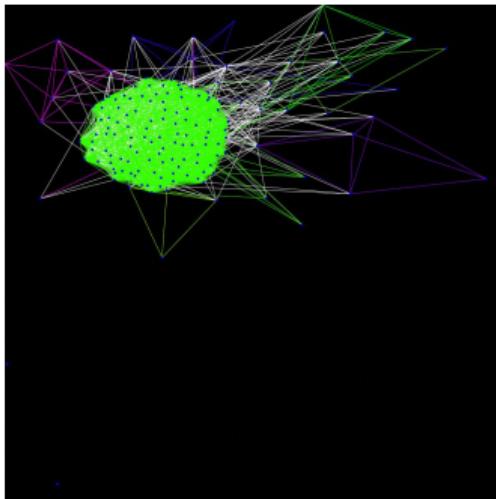
d4 Compiler

github.com/SoftVarE-Group/d4v2

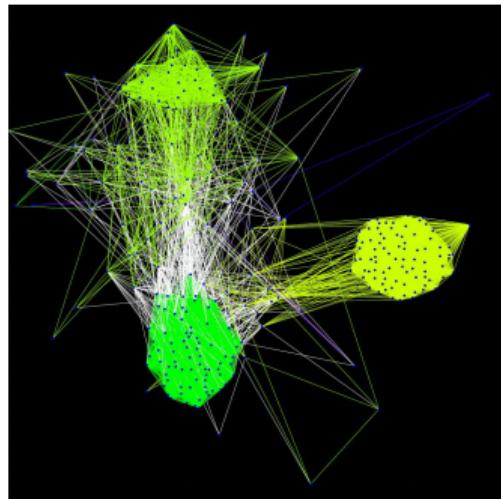
Community detection



Original CNF



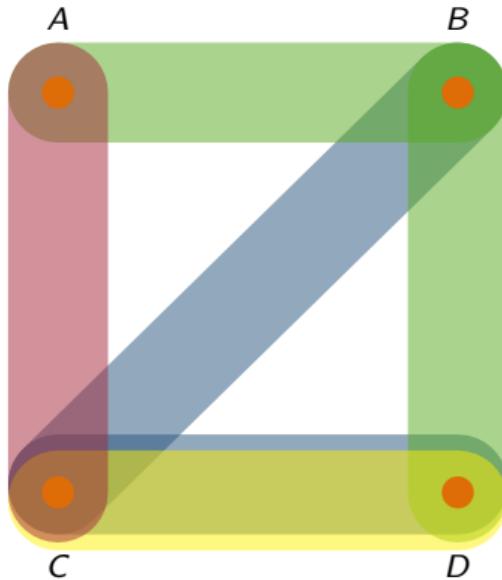
Block 1



Block 2

Hypergraphs

$$(B \vee C \vee D) \wedge (A \vee B \vee D) \wedge (A \vee C) \wedge (C \vee D)$$



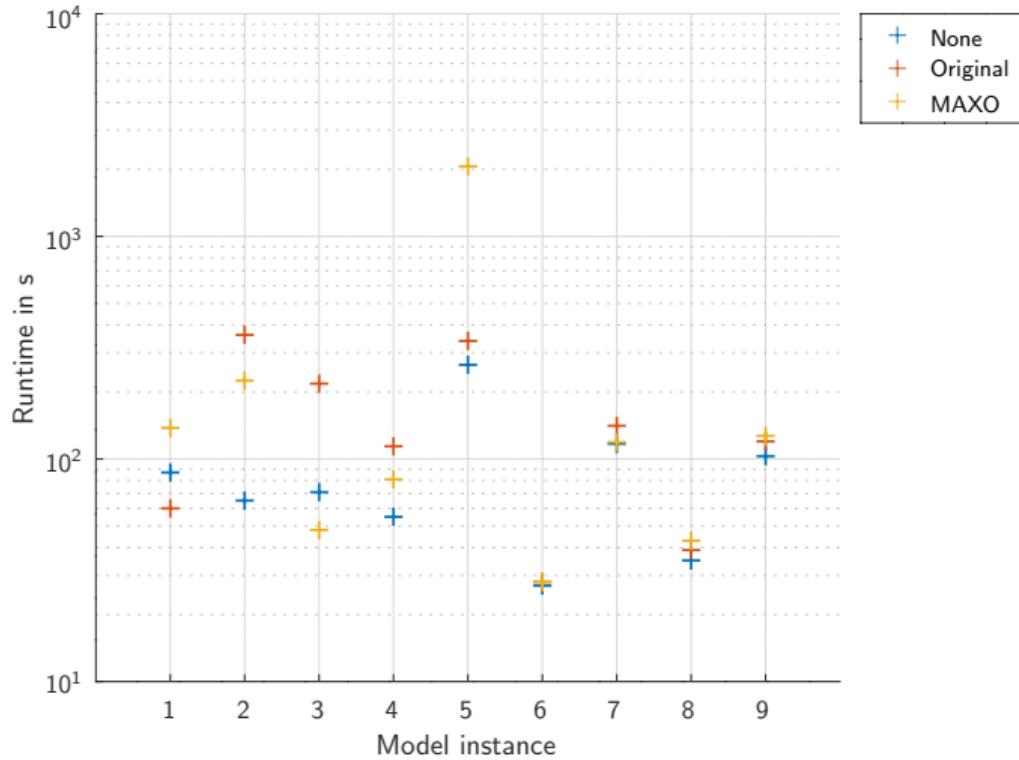
Pin

Connection between net and vertex.

$$P = (n, v)$$

Community detection

d4 runtime by partitioning method



Community detection

d4 runtime by partitioning method

